

# Response of First Order Systems to Sinusoidal Input

## First Order System - Sinusoidal Input

○ Consider the following first order system:

$$G(s) = \frac{O(s)}{I(s)} = \frac{1}{\tau s + 1}$$

Determine the response of the system if input is a sinusoidal:

$$I(t) = A \sin(\omega t)$$

Which may be transformed to:

$$I(s) = \frac{A\omega}{s^2 + \omega^2}$$

the system response,  $O(s)$ , is then:

$$O(s) = \frac{A \frac{\omega}{\tau}}{(s + \frac{1}{\tau})(s^2 + \omega^2)} = \frac{a}{s + \frac{1}{\tau}} + \frac{b}{s + i\omega} + \frac{c}{s - i\omega}$$

○ Solving then for a, b, and c:

## First Order System - Sinusoidal Input

To solve for a, multiply by  $s + 1/\tau$ , and let  $s = -1/\tau$

$$\frac{A \frac{\omega}{\tau}}{\frac{1}{\tau^2} + \omega^2} = a = \frac{A \tau \omega}{1 + \tau^2 \omega^2}$$

To solve for b, multiply by  $s + i\omega$ , and let  $s = -i\omega$

$$\frac{A \frac{\omega}{\tau}}{(-i\omega + \frac{1}{\tau})(-i\omega - i\omega)} = \frac{A \frac{\omega}{\tau}}{2i^2 \omega^2 - \frac{2i\omega}{\tau}} = \frac{A}{i^2 2\tau\omega - 2i} =$$
$$b = \frac{-\frac{A}{2}}{\tau\omega + i} \left( \frac{\tau\omega - i}{\tau\omega - i} \right) = \frac{-\frac{A}{2}(\tau\omega - i)}{\tau^2 \omega^2 + 1}$$

## First Order System - Sinusoidal Input

c will be the complex conjugate of b and is:

$$c = \frac{-\frac{A}{2}(\tau\omega + i)}{\tau^2\omega^2 + 1}$$

Using the solution in the S&C for a sinusoidal function, the solution becomes:

$$L^{-1}\left[\frac{B + iC}{s - r - i\omega} \frac{B - iC}{s - r + i\omega}\right] = 2\sqrt{B^2 + C^2} e^{rt} \sin(\omega t + \phi)$$

$$\text{Where: } \phi = \tan^{-1}\left(\frac{C}{B}\right) \quad C = \left(\frac{A}{\tau^2\omega^2 + 1}\right)\left(\frac{1}{2}\right) \quad B = \left(\frac{-A}{\tau^2\omega^2 + 1}\right)\left(\frac{\tau\omega}{2}\right), r = 0$$

$$2\left(\frac{A}{\tau^2\omega^2 + 1}\right)\left(\frac{1}{2}\right)\sqrt{\tau^2\omega^2 + 1}(e^{0t})\sin(\omega t + \phi) \quad \phi = \tan^{-1}(-\tau\omega)$$

## First Order System - Sinusoidal Input

The complete solution is then:

$$O(t) = \frac{A\tau\omega}{\tau^2\omega^2 + 1} e^{-\frac{t}{\tau}} + \left( \frac{A}{\sqrt{\tau^2\omega^2 + 1}} \right) \sin(\omega t + \phi)$$

It is important to note that the solution is made-up of a transient (the first term) and a non-transient part (the second term).

Consider simply substituting  $i\omega$  for  $s$  in the original transfer function and solving for  $|G(i\omega)|$   $\angle G(i\omega)$

$$G(i\omega) = \frac{1}{\tau i\omega + 1} \quad G(i\omega) = \frac{1}{\tau i\omega + 1} = \frac{i\tau\omega - 1}{i^2\tau^2\omega^2 - 1} = -\frac{i\tau\omega - 1}{\tau^2\omega^2 + 1} = \frac{1 - i\tau\omega}{\tau^2\omega^2 + 1}$$

$$|G(i\omega)| = \sqrt{\text{Im}(G(i\omega))^2 + \text{Re}(G(i\omega))^2} = \sqrt{\left(\frac{\tau\omega}{\tau^2\omega^2 + 1}\right)^2 + \left(\frac{1}{\tau^2\omega^2 + 1}\right)^2} = \frac{1}{\sqrt{\tau^2\omega^2 + 1}}$$

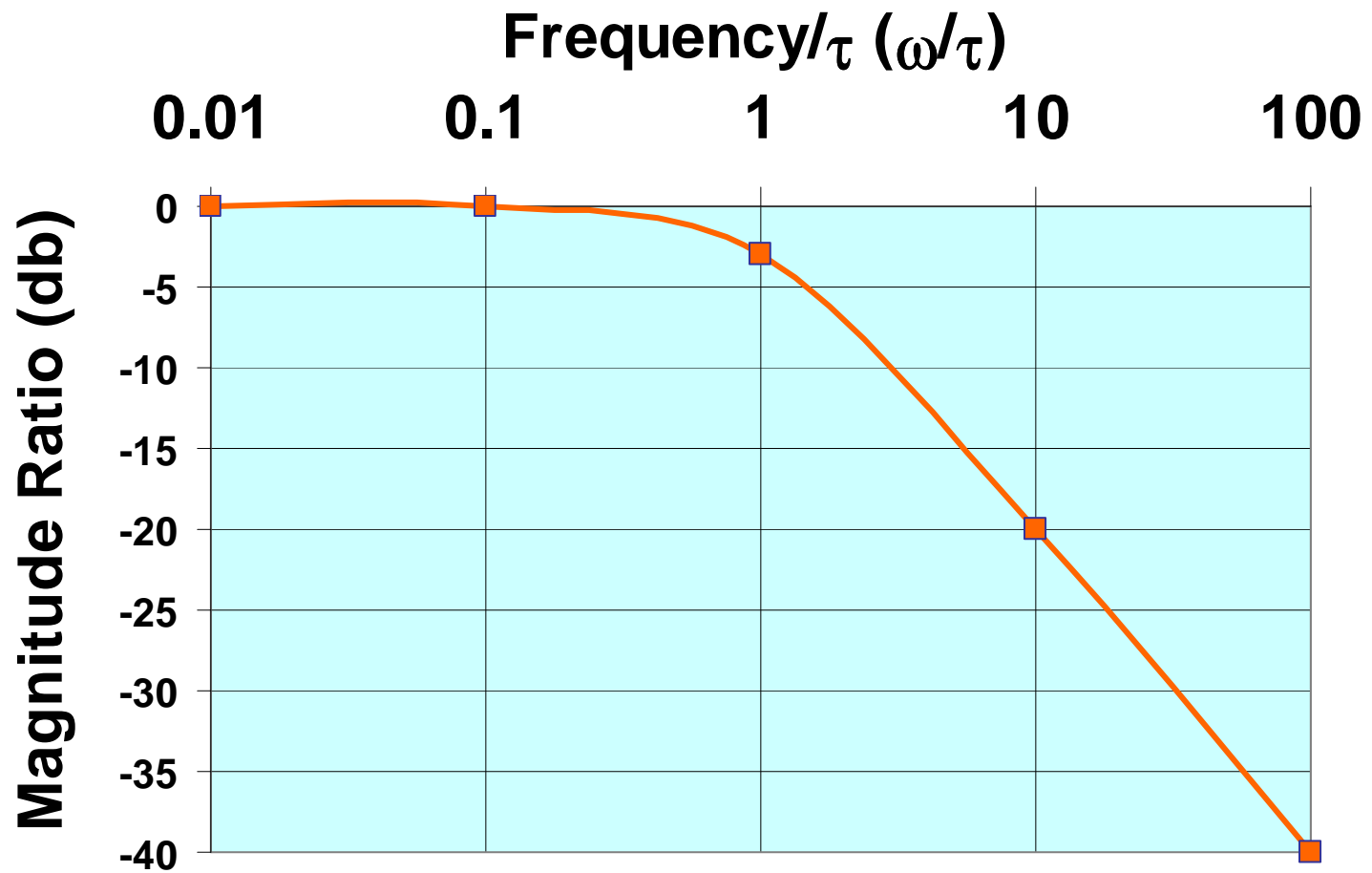
$$\angle G(i\omega) = \tan^{-1}\left(\frac{\text{Im}(G(i\omega))}{\text{Re}(G(i\omega))}\right) = \tan^{-1}(-\tau\omega) \quad \text{Note, this gives us the non-transient solution}$$

## Plotting Frequency response

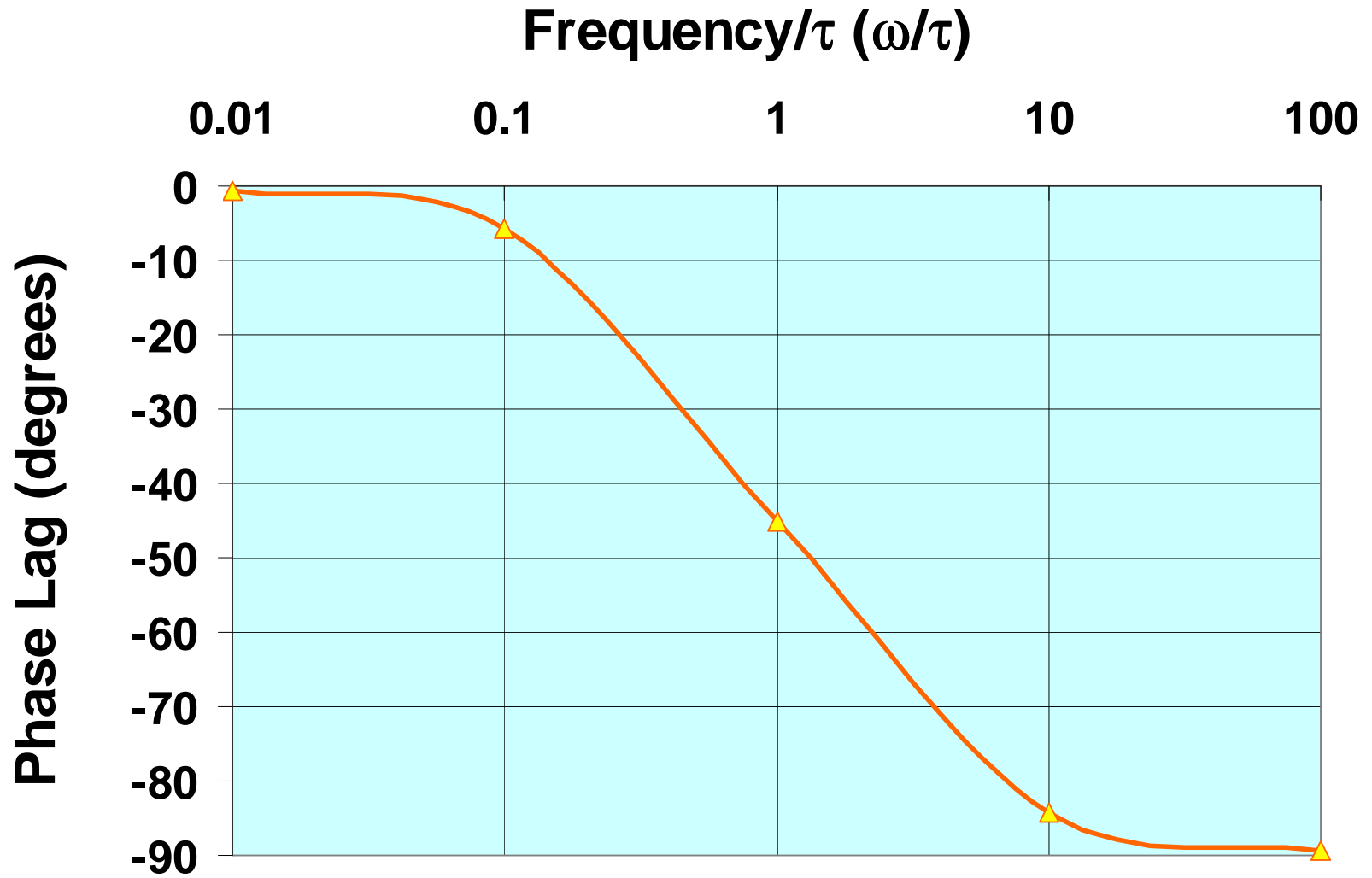
$$|G(i\omega)| = \frac{1}{\sqrt{\tau^2 \omega^2 + 1}}$$
$$\angle G(i\omega) = \tan^{-1}(-\tau\omega)$$

$\omega$	$G(i\omega)$	$20\log(G(i\omega))$	$\phi$
$0.01/\tau$	<b>1</b>	<b>0</b>	$-0.5729$
$0.1/\tau$	<b>1</b>	<b>0</b>	$-5.7106$
$1/\tau$	<b>0.7071</b>	<b>-3</b>	$-45$
$10/\tau$	<b>0.1</b>	<b>-20</b>	$-84.289$
$100/\tau$	<b>0.01</b>	<b>-40</b>	$-89.427$

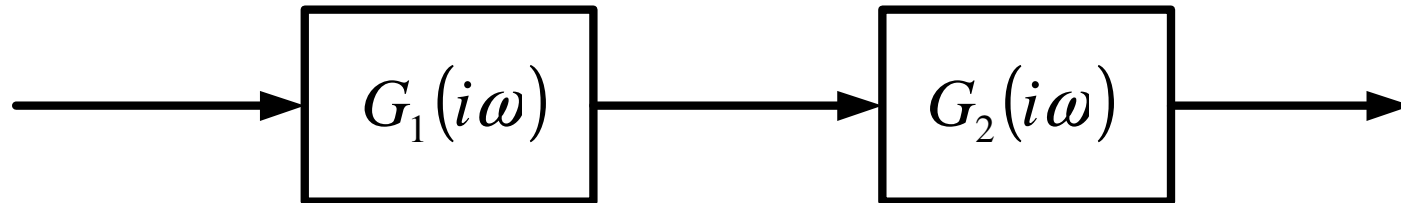
## Plotting Frequency response



# Plotting Frequency response



## Adding terms of Frequency Response



$$20 \log(|G_1(i\omega)| |G_2(i\omega)|) = 20 \log(|G_1(i\omega)|) + 20 \log(|G_2(i\omega)|)$$

$$\angle G_1(i\omega) G_2(i\omega) = \angle G_1(i\omega) + \angle G_2(i\omega)$$

**We can simply add terms on the Bode Magnitude plot and on the Bode Phase plot to get total response**